

제 3 장

Action-angle variables and Liouville's theorem

Canonical transformation이 사용되는 가장 대표적인 예는 동역학 문제를 action과 angle이라는 두 개의 변수로 표현하는 것이다. 이 경우 Hamiltonian 역학을 매우 단순하게 취급할 수 있도록 해주기 때문에, 가속기물리에서 매우 유용하다. 이 장 후반부에서는 Liouville's theorem을 Hamiltonian 역학의 관점에서 공부한다. Liouville's theorem is crucial for understanding the fundamental properties of large ensembles of beam particles in accelerators.

제 1 절 Canonical Transformation for a Linear Oscillator

An illustrative example of the canonical transformation: a simple harmonic oscillator

- The Hamiltonian for an oscillator with a unit mass:

$$H(x, p) = \frac{p^2}{2} + \frac{\omega_0^2 x^2}{2}, \quad (3.1)$$

- The equations of motion:

$$\dot{p} = -\frac{\partial H}{\partial x} = \omega_0^2 x, \quad \dot{x} = \frac{\partial H}{\partial p} = p, \quad (3.2)$$

- Solution:

$$x = a \cos(\omega_0 t + \phi_0), \quad p = -a\omega_0 \sin(\omega_0 t + \phi_0), \quad (3.3)$$

- We would like to find a canonical transformation from the old variables, x, p , to the new ones, ϕ, I , (where ϕ is the new coordinate and I is the new momentum):

$$x = A(I) \cos \phi, \quad p = -A(I) \omega_0 \sin \phi, \quad (3.4)$$

식 (3.3)과 비교를 하면, $a \rightarrow A(I)$ 에 대응되므로, I 는 constant of motion이고, $\omega_0 t + \phi_0 \rightarrow \phi$ 이므로, ϕ 는 시간에 대한 선형 함수이다.

- To construct the canonical transformation (3.4) we will use the generating function $F_1(x, \phi)$ of the first type.
- First, we express p in terms of the old (x) and new (ϕ) coordinates by eliminating $A(I)$ from (3.4):

$$p = -\omega_0 x \tan \phi. \quad (3.5)$$

- 2장에 소개된 F_1 에 대한 미분식을 적분하면, F_1 을 얻을 수 있다. 여기서는 적분 상수는 없어도 됨.

$$\left(\frac{\partial F_1}{\partial x} \right)_\phi = p = -\omega_0 x \tan \phi$$

$$F_1(x, \phi) = \int p dx = -\frac{\omega_0 x^2}{2} \tan \phi. \quad (3.6)$$

- F_1 을 다시 새로운 좌표계에 대해 미분하면, 새로운 momentum을 얻을 수 있다.

$$I = -\frac{\partial F_1}{\partial \phi} = \frac{\omega_0 x^2}{2} (1 + \tan^2 \phi) = \frac{1}{2\omega_0} (\omega_0^2 x^2 + p^2), \quad (3.7)$$

- By substituting Eq. (3.4) into (3.7):

$$A(I) = \sqrt{\frac{2I}{\omega_0}}. \quad (3.8)$$

- The new coordinate in terms of old variables:

$$\phi = -\arctan \frac{p}{\omega_0 x}. \quad (3.9)$$

- Because the canonical transformation does not depend on time, the new Hamiltonian is equal to the old one expressed in new variables.

$$H' = H + \frac{\partial F_1}{\partial t} = H$$

- Comparing Eq. (3.1) with (3.7):

$$H' = \omega_0 I. \quad (3.10)$$

I 의 단위는 ? [에너지] \times [시간]

- The equations of motion in new variables

$$\dot{I} = -\frac{\partial H'}{\partial \phi} = 0, \quad \dot{\phi} = \frac{\partial H'}{\partial I} = \omega_0. \quad (3.11)$$

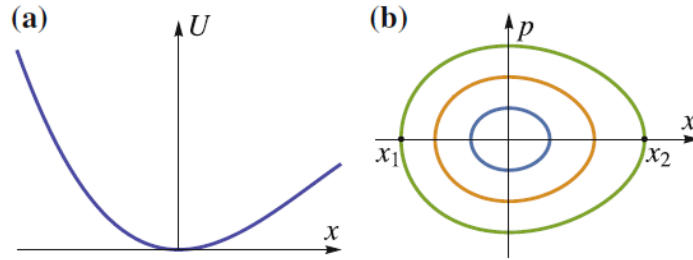
$$I = \text{const}, \quad \phi = \omega_0 t + \phi_0. \quad (3.12)$$

Of course, this is the same dynamics as described by the original Eq. (3.3), but it is simpler because one of the coordinates, I , turns out to be an integral of motion and the other one, ϕ , is a simple linear function of time.

- The (I, ϕ) pair is called the *action-angle* coordinates for this particular case. They are especially useful for building perturbation theory for more complicated systems that in the lowest approximation reduce to a linear oscillator.

제 2 절 Action-Angle Variables in 1D

We can generalize the action-angle variables introduced in the previous section to 1D periodic (x 가 에너지에 따라 주어진 구간을 반복해서 왕복운동) motion in an *arbitrary* but constant (시간에 대해 의존하지 않는다는 이야기) potential well $U(x)$. $U(x) \propto x^2$ 인 특별한 경우가 simple harmonic oscillator 에 해당.



2.1 Energy E 를 새로운 모멘텀으로 한 경우

- Hamiltonian for this problem (assuming a unit mass):

$$H(x, p) = \frac{p^2}{2} + U(x). \quad (3.13)$$

- Each trajectory in phase space is defined by a constant value of the Hamiltonian, $H(x, p) = E$, where E is the energy.
- Both x and p for a given trajectory are periodic functions of time oscillating with the revolution frequency ω that depends on the energy, $\omega(E)$.

$$\frac{dx}{dt} = p = \sqrt{2(E - U(x))} \quad (\because m = 1) \quad (3.14)$$

$$\frac{1}{2}T = \pi\omega^{-1} = \int_{x_1}^{x_2} \frac{dx'}{p(x')} = \int_{x_1}^{x_2} \frac{dx'}{\sqrt{2(E - U(x'))}}, \quad (3.15)$$

where $T = 2\pi/\omega$ is the period, and x_1 and x_2 are the turning points on the orbit.

- Canonical transformation from (x, p) to (Q, E) : $F_2(x, E)$

$$\frac{\partial F_2}{\partial x} = p = \sqrt{2(E - U(x))} \quad (3.16)$$

$$F_2(x, E) = \int^x dx' \sqrt{2(E - U(x'))}. \quad (3.17)$$

- This is a time-independent transformation.

$$H'(Q, E) = H + \cancel{\frac{\partial F_2}{\partial t}} = E, \quad (3.18)$$

- Equations of motion for the new variables:

$$\dot{Q} = \frac{\partial H'}{\partial E} = 1, \quad \dot{E} = -\frac{\partial H'}{\partial Q} = 0. \quad (3.19)$$

- The evolution of the variable Q is simple.

$$Q = t + t_0. \quad (3.20)$$

- 문제점: 한 바퀴를 돌고 나면, Q 는 한 주기 $T = 2\pi/\omega(E)$ 만큼 증가하게 되는데, 이 주기가 E 의 함수가 되어버려서, 에너지 E 에 따라 각각의 궤적의 주기가 달라지게 된다.

2.2 Action J 를 새로운 모멘텀으로 한 경우

좀더 좋은 방법은 새로운 좌표계로 각도 (angle) ϕ 를 잡아서, 한 주기 후에는 모든 궤적이 2π 만큼 공통적으로 움직이도록 하는 것이다.

- The new coordinate ϕ is called the *angle*, and the corresponding generalized momentum, J , is the *action*.
- Canonical transformation from (x, p) to (ϕ, J) : $\tilde{F}_2(x, J)$
- The action is a function of energy, $J(E)$, or, conversely, $E = E(J)$.
- The generating function is only slightly modified.

$$\tilde{F}_2(x, J) = F_2(x, E(J)). \quad (3.21)$$

- As the Hamiltonian is time-independent, the new Hamiltonian is

$$\tilde{H}(\phi, J) = E(J), \quad (3.22)$$

- The equations of motion for the new variables:

$$\dot{\phi} = \frac{\partial \tilde{H}}{\partial J} = \frac{dE}{dJ} = \omega(E), \quad \dot{J} = -\frac{\partial \tilde{H}}{\partial \phi} = 0. \quad (3.23)$$

- Integrating the equation with $\dot{\phi} = \omega(E)$ gives

$$\phi = \omega(E)t + \phi_0. \quad (3.24)$$

With this time dependence, one orbital period corresponds to the change of ϕ by 2π , as desired. 정의에 의해 $\omega(E)T = 2\pi$ 이다.

- Integrating the differential equation for $E(J)$

$$\frac{dE}{dJ} = \omega(E). \quad (3.25)$$

$$J(E) = \int_{E_{\min}}^E \frac{dE'}{\omega(E')}, \quad (3.26)$$

where E_{\min} is the energy corresponding to the bottom of the potential well U .

NOTES

- Generating function 이 꼭 해석해로 존재할 필요는 없다. 수치해로 존재해도 상관없음.
- The key features of action-angle coordinates are that the action is a constant of the motion, and the angle grows linearly in time, with periodic motion corresponding to a change in phase of 2π .
- The rate of change in the phase ($\dot{\phi} = \omega(E)$) is generally different for different trajectories. The simple harmonic oscillator is a notable exception where all trajectories have the same period ($\dot{\phi} = \omega_0$).

제 3 절 Hamiltonian Flow in Phase Space and Symplectic Maps

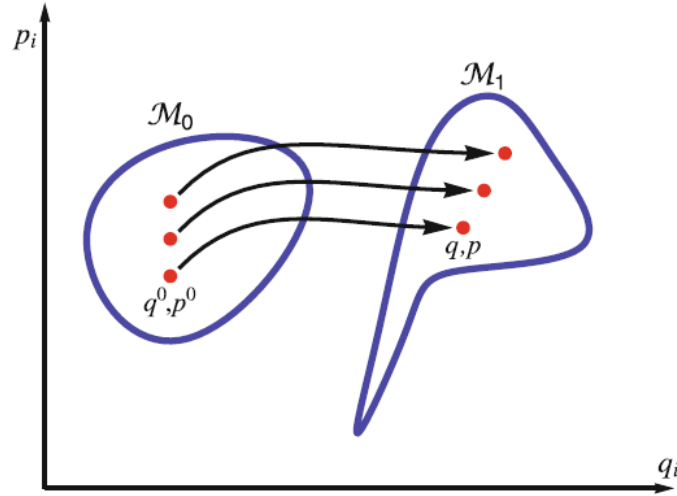
3.1 Hamiltonian 운동을 기하학적인 관점으로 보기

- A *map* of the initial domain in the $2n$ dimensional phase space to a manifold (다양체) in the same phase space at time t :

$$q_i = q_i(q_k^0, p_k^0, t_0, t), \quad p_i = p_i(q_k^0, p_k^0, t_0, t). \quad (3.27)$$

Varying t in these equations moves each point (q_i, p_i) along its trajectory and the set of all trajectories starting from the initial domain constitutes a *Hamiltonian flow*.

- For a given t_0 and t , Eq. (3.27) constitute a canonical transformation from q_i^0, p_i^0 to q_i, p_i , which is also called a *symplectic transfer map*.



3.2 $n = 1$ 인 경우에 대하여, symplectic transfer map 이 canonical transformation 이 됨을 증명

- 먼저, $t = t_0$ 에 대하여 아래의 사실은 자명함.

$$\{q, p\}_{q^0, p^0} = 1, \quad \{p, p\}_{q^0, p^0} = \{q, q\}_{q^0, p^0} = 0 \quad (3.28)$$

- $\{p, p\}_{q^0, p^0} = \{q, q\}_{q^0, p^0} = 0$ 은 시간에 관계 없이 항상 자명하게 성립.

- 따라서, 위의 Poisson bracket 중 $\{q, p\}_{q^0, p^0}$ 이 시간에 대해 변하지 않는다는 것만 보이면, 증명이 끝남.

$$\begin{aligned}
\frac{d}{dt}\{q, p\}_{q^0, p^0} &= \frac{d}{dt} \left(\frac{\partial q}{\partial q^0} \frac{\partial p}{\partial p^0} - \frac{\partial q}{\partial p^0} \frac{\partial p}{\partial q^0} \right) \\
&= \frac{\partial p}{\partial p^0} \frac{\partial}{\partial q^0} \frac{dq}{dt} + \frac{\partial q}{\partial q^0} \frac{\partial}{\partial p^0} \frac{dp}{dt} - \frac{\partial p}{\partial q^0} \frac{\partial}{\partial p^0} \frac{dq}{dt} - \frac{\partial q}{\partial p^0} \frac{\partial}{\partial q^0} \frac{dp}{dt} \\
&= \frac{\partial p}{\partial p^0} \frac{\partial}{\partial q^0} \frac{\partial H}{\partial p} - \frac{\partial q}{\partial q^0} \frac{\partial}{\partial p^0} \frac{\partial H}{\partial q} - \frac{\partial p}{\partial q^0} \frac{\partial}{\partial p^0} \frac{\partial H}{\partial p} + \frac{\partial q}{\partial p^0} \frac{\partial}{\partial q^0} \frac{\partial H}{\partial q}.
\end{aligned} \tag{3.29}$$

Applying the chain rules,

$$\frac{\partial}{\partial p^0} = \frac{\partial p}{\partial p^0} \frac{\partial}{\partial p} + \frac{\partial q}{\partial p^0} \frac{\partial}{\partial q}, \quad \frac{\partial}{\partial q^0} = \frac{\partial p}{\partial q^0} \frac{\partial}{\partial p} + \frac{\partial q}{\partial q^0} \frac{\partial}{\partial q}, \tag{3.30}$$

we obtain

$$\frac{d}{dt}\{q, p\}_{q^0, p^0} = 0 \tag{3.31}$$

보충: Interchange property of partial and ordinary derivatives

Let $f = f(q, p, t)$. The ordinary derivative of f with respect to t is

$$\frac{df}{dt} = \frac{\partial f}{\partial q} \dot{q} + \frac{\partial f}{\partial p} \dot{p} + \frac{\partial f}{\partial t} \tag{3.32}$$

$$\frac{\partial}{\partial q} \left(\frac{df}{dt} \right) = \frac{\partial^2 f}{\partial q \partial q} \dot{q} + \frac{\partial^2 f}{\partial q \partial p} \dot{p} + \frac{\partial^2 f}{\partial q \partial t} \tag{3.33}$$

$$\frac{d}{dt} \left(\frac{\partial f}{\partial q} \right) = \frac{\partial^2 f}{\partial q \partial q} \dot{q} + \frac{\partial^2 f}{\partial p \partial q} \dot{p} + \frac{\partial^2 f}{\partial t \partial q} \tag{3.34}$$

Therefore,

$$\frac{\partial}{\partial q} \left(\frac{df}{dt} \right) = \frac{d}{dt} \left(\frac{\partial f}{\partial q} \right) \tag{3.35}$$

여기서, \dot{q} 및 \dot{p} 는 q 에 독립적인 변수로 간주.

3.3 Symplectic maps

Canonical transformation Eq. (3.27) 을 종종 symplectic (transfer) map 으로 기술하기 위해 아래의 block-diagonal $2n \times 2n$ antisymmetric matrix 를 도입.

$$J_{2n} = \begin{pmatrix} J_2 & 0 & 0 & 0 \\ 0 & J_2 & 0 & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & 0 & J_2 \end{pmatrix}, \tag{3.36}$$

The diagonal elements are

$$J_2 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \quad (3.37)$$

주의: Wolski 책에서는 $J_2 \rightarrow -J_2 = S_2$ 로 정의됨.

- Notation for $2n$ variables consistent with the definition of J_{2n} :

$$w_k : \quad w_{2k-1} = q_k, \quad w_{2k} = p_k, \quad k = 1, 2, \dots, n \quad (3.38)$$

$$W_i : \quad W_{2i-1} = Q_i, \quad W_{2i} = P_i, \quad i = 1, 2, \dots, n \quad (3.39)$$

- The transformation from the old to new variables (2.2) is then replaced by $2n$ functions as

$$W_i = W_i(w_k, t), \quad i, k = 1, 2, \dots, 2n. \quad (3.40)$$

즉, 위의 식은 아래와 등가적임.

$$Q_i = Q_i(q_k, p_k, t), \quad P_i = P_i(q_k, p_k, t), \quad i = 1, \dots, n \quad (3.41)$$

- The requirement that all possible Poisson brackets satisfy Eqs. (2.15)–(2.17) (which, as we know, is equivalent to the requirement for the transformation to be canonical) can be concisely written as

$$MJ_{2n}M^T = J_{2n}, \text{ or } M^T J_{2n}M = J_{2n} \quad (3.42)$$

where M is the Jacobian matrix of the transformation

$$M_{ij} = \frac{\partial W_i}{\partial w_j} \quad (3.43)$$

A transformation with Jacobian satisfying Eq. (3.42) is said to be *symplectic*. The Jacobian of a canonical transformation is a symplectic matrix.

- Both the matrix and its determinant are referred to as the Jacobian in some literatures.

보충: Proof that Jacobian matrix of a canonical transformation is symplectic (A. Wolski 책 내용)

Hamiltonian equations with old and new variables:

$$\dot{w}_i = S_{ik} \frac{\partial H}{\partial w_k}, \quad \dot{W}_i = S_{ik} \frac{\partial H}{\partial W_k}, \quad i, k = 1, 2, \dots, 2n \quad (3.44)$$

Here,

$$S = \begin{pmatrix} S_2 & 0 & 0 & 0 \\ 0 & S_2 & 0 & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & 0 & S_2 \end{pmatrix} = -J_{2n},$$

Consider an infinitesimal change in the independent variable from t_0 to $t_0 + \delta t$:

$$W_i(t_0 + \delta t) = W_i(t_0) + \dot{W}_i(t_0)\delta t = w_i(t_0) + \dot{w}_i(t_0)\delta t = w_i + S_{ik} \left(\frac{\partial H}{\partial w_k} \right)_{t_0} \delta t \quad (3.45)$$

From the definition of the Jacobian of the transformation from t_0 to $t_0 + \delta t$ (we note that $S_{ii} = 0$)

$$M_{ij} = \frac{\partial W_i(t_0 + \delta t)}{\partial w_j} = \delta_{ij} + S_{ik} \left(\frac{\partial^2 H}{\partial w_j \partial w_k} \right)_{t_0} \delta t = \delta_{ij} + S_{ik} \tilde{H}_{kj} \delta t \quad (3.46)$$

Or, in the matrix notation

$$M = I + S \tilde{H} \delta t \quad (3.47)$$

To first order in δt

$$(I + S \tilde{H} \delta t) S (I + S \tilde{H} \delta t)^T = (I + S \tilde{H} \delta t) S (I - \tilde{H} S \delta t) = S \quad (3.48)$$

Or, equivalently,

$$(I + S \tilde{H} \delta t)^T S (I + S \tilde{H} \delta t) = (I - \tilde{H} S \delta t) S (I + S \tilde{H} \delta t) = S \quad (3.49)$$

If we think of expansion of W_i about the reference orbit:

$$W_i(w_j, t_0 + \delta t) = W_i(0, t_0 + \delta t) + \sum_j \frac{\partial W_i(0, t_0 + \delta t)}{\partial w_j} w_j = \sum_j M_{ij}(0) w_j \quad (3.50)$$

Here, we assume that the reference orbit is transformed to a reference orbit when there is no constant force term (i.e, linear term in the Hamiltonian), and set $W_i(0, t_0 + \delta t) = 0$.

NOTES

1. 만약, H 가 w_i 에 대한 2차식으로만 이루어져 있다면 (즉, 운동방정식이 선형이라면), $M_{ij}(0) = M_{ij}$ 이고 mapping 을 다음과 같이 행렬 형태로 표현할 수 있다.

$$W_i(t_0 + \delta t) = M_{ij} w_j \quad (3.51)$$

2. 만약, H 가 w_i 에 대한 1, 2차식 모두로 이루어져 있다면 0th order 항이 생긴다.

$$W_i(t_0 + \delta t) = M_{ij} w_j + m_i \quad (3.52)$$

3. 만약, 예 1에서 H 가 시간에 대한 의존성이 없고 $t = t_0 + N\delta t = t_0 + \Delta t$ 에서 계산하면

$$W_i(t_0 + \Delta t) = [I + S\tilde{H}\delta t]_{ij}^N w_j \simeq [I + S\tilde{H}\Delta t]_{ij} w_j \quad (3.53)$$

4. 만약, 예 1에서 H 가 piece-wise constant 하다면, 즉, Δt_1 동안에 H_1 을 가지고, Δt_2 동안에 H_2 을 가지고, 등등

$$W_i(t_0 + \Delta t_1 + \Delta t_2 + \dots) = \left[(\dots)(I + S\tilde{H}_2\Delta t_2)(I + S\tilde{H}_1\Delta t_1) \right]_{ij} w_j \quad (3.54)$$

5. 기본적으로 예 3, 4 에서는 Δt 등이 모두 매우 작을 때 이며, 그렇지 않을 경우 higher-order 항들을 모두 고려해야 한다. 예를 들면 quadrupole 의 transfer matrix 는 아래와 같이 주어진다. 이 식은 기본적으로 운동방정식을 직접 풀어서 $W_i = M_{ij}w_j$ 로 표현한 후, $M_{ij} = \partial W_i / \partial w_j$ 를 계산한 것이다. 즉, 모든 higher-order 항들 고려한 것이된다.

$$M_{ij} = \begin{pmatrix} \cos(\sqrt{k}l) & \frac{\sin(\sqrt{k}l)}{\sqrt{k}} \\ -\sqrt{k} \sin(\sqrt{k}l) & \cos(\sqrt{k}l) \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & l \\ -kl & 1 \end{pmatrix} \quad (3.55)$$

우변의 근사는 l (또는 이 논의에서는 Δt 에 해당) 을 매우 작다고 가정하여 얻은 것이며, 이 경우 Hamiltonian 으로 부터 Jacobian matrix 를 계산하여서도 얻을 수 있다.

$$H = \frac{p_x^2}{2} + \frac{k}{2}x^2 \quad (3.56)$$

$$\tilde{H}_{kj} = \left(\frac{\partial^2 H}{\partial w_j \partial w_k} \right)_{t_0} \longrightarrow \begin{pmatrix} k & 0 \\ 0 & 1 \end{pmatrix} \quad (3.57)$$

$$M_{ij} = \delta_{ij} + S_{ik} \tilde{H}_{kj} l \longrightarrow \begin{pmatrix} 1 & l \\ -kl & 1 \end{pmatrix} \quad (3.58)$$

제 4 절 Liouville's Theorem

- Volume of the old phase space domain:

$$V_1 = \int_{\mathcal{M}_0} dq_1 dq_2 \dots dq_n dp_1 dp_2 \dots dp_n, \quad (3.59)$$

- Volume of the new phase space domain:

$$V_2 = \int_{\mathcal{M}_1} dQ_1 dQ_2 \dots dQ_n dP_1 dP_2 \dots dP_n. \quad (3.60)$$

- It turns out that $V_2 = V_1$.

- Proof: The ratio of infinitesimal volumes in a transformation of variables is equal to the absolute value of the determinant of the Jacobian matrix of the transformation.

$$\frac{dQ_1 dQ_2 \dots dQ_n dP_1 dP_2 \dots dP_n}{dq_1 dq_2 \dots dq_n dp_1 dp_2 \dots dp_n} = |\det M|. \quad (3.61)$$

Since,

$$\det(M J_{2n} M^T) = (\det M)^2 \det(J_{2n}) = \det(J_{2n}) = 1 \quad (3.62)$$

Therefore, $|\det(M)| = 1$.

- Liouville's theorem guarantees that the phase space volume occupied initially by a beam remains the same through its Hamiltonian evolution with time.

보충: Distribution function

- It is a continuous (mathematical) approximation of discrete (real) particle distribution.
- The number of particles found in a differential volume in the neighborhood of a phase space location x, p at a time t :

$$f(\mathbf{x}, \mathbf{p}, t) d^3 \mathbf{x} d^3 \mathbf{p} \quad (3.63)$$

- With a smooth phase space distribution, the charge and current distributions associated with such a distribution are also continuous and smooth.
- The fields derived from the smooth charge/current densities may be termed macroscopic. Deviations from these approximate fields (near an individual particle) may be termed microscopic.

보충: Proof of Liouville's theorem

- Total time derivative of the distribution function:

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \dot{\mathbf{x}} \cdot \nabla f + \dot{\mathbf{p}} \cdot \nabla_{\mathbf{p}} f \quad (3.64)$$

- From continuity in phase-space:

$$0 = \frac{\partial f}{\partial t} + \nabla \cdot (\dot{\mathbf{x}} f) + \nabla_{\mathbf{p}} \cdot (\dot{\mathbf{p}} f) \quad (3.65)$$

- If the forces are derivable from a Hamiltonian, then

$$\begin{aligned} \frac{df}{dt} &= \frac{\partial f}{\partial t} + \sum_i \left(\frac{dx_i}{dt} \frac{\partial f}{\partial x_i} + \frac{dp_i}{dt} \frac{\partial f}{\partial p_i} \right) \\ &= - \sum_i \left(\frac{\partial \dot{x}_i}{\partial x_i} f + \frac{\partial \dot{p}_i}{\partial p_i} f \right) = - \sum_i f \left[\frac{\partial}{\partial x_i} \left(\frac{\partial H}{\partial p_i} \right) - \frac{\partial}{\partial p_i} \left(\frac{\partial H}{\partial x_i} \right) \right] = 0 \end{aligned}$$

- In other words, when no dissipative forces, no particle lost or created, and no small-impact-parameter binary Coulomb collisions between particles, we have

$$\frac{df}{dt} = 0 \quad (3.66)$$

- Incompressibility:

$$\nabla \cdot (\dot{\mathbf{x}}) + \nabla_{\mathbf{p}} \cdot (\dot{\mathbf{p}}) = 0 \quad (3.67)$$

보충: Comments on Liouville's theorem

- Liouville's theorem states that the phase space density encountered as one travels with a particle in a Hamiltonian system is conserved.
 - The density of any volume of phase space whose boundary follows the Hamiltonian equations is constant.
 - The volume occupied by particles in phase space (\sim emittance) is conserved (shape may change).
- Liouville's theorem is valid not only for the time-independent Hamiltonian case, but also for the time-dependent Hamiltonian case.
- Liouville's theorem is valid for both equilibrium and non-equilibrium systems.
- Liouville's theorem is valid for both linear and non-linear systems.
- Liouville's theorem does not imply that the density is uniform throughout phase space.
- Liouville's theorem only holds in the limit that the particles are infinitely close together. Equivalently, Liouville's theorem does not hold for any ensemble that consists of a finite number of particles.
- Liouville's theorem holds even in the presence of space-charge and wake-fields, but not with microscopic binary collisions.

보충: Meaning of equilibrium

- Any positive-definite (because it should represent particle counts) distribution function formed from a set of single-particle constants of the motion $\{C_i\}$ will produce a valid, exact 'equilibrium' solution to the Vlasov equation.

$$\frac{d}{dt}f(\{C_i\}) = 0 \quad (3.68)$$

- A special case is a stationary (time-independent) equilibrium with $\partial/\partial t = 0$. Stationary beam equilibria occur in continuous-focusing systems.

- In continuous-focusing systems, one may assume the beam is in thermal equilibrium

$$f \propto \exp \left[-\frac{H}{k_B T_{eq}} \right], \quad \frac{\partial f}{\partial t} = 0, \quad (3.69)$$

where H is a constant of the motion for a time-independent Hamiltonian,

- In non-continuous lattices, projections of the distribution can evolve in t .
- In the periodic focusing system, the particle distribution is non-stationary, however, when plotted in trace space once per period (i.e., in the Poincare plot), we can treat the beam in stationary equilibrium.

$$f(t) = f(t + T) \quad (3.70)$$

제 5 절 Non-conservative Forces in Hamiltonian Dynamics

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